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THERMAL FOOTPRINT DETECTION

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Abstract: A method is presented which extracts a low contrast thermal human footprint from its surroundings. It uses a novel operator to combine separate blobs in the image without introducing unnecessary clutter. The morphological operation of dilation has been demonstrated on a binary image using the new operator, though the method should be extensible to other operations and to grey scale images.

1. Introduction

In an attempt to make persons and property more secure the use of video cameras is increasing, but the success or otherwise of such devices depends heavily on the recognition of a threat if it occurs in the image. Human observers are prone to drowsiness and error, and a larger role is being played by artificial intelligence (AI) in threat recognition. Sensors too are improving, and the combination of new sensors and AI provides opportunities for higher levels of security.

Multiple pyroelectric detectors were used for tracking people (Hobbs, 2001), but these sensors generally have low (spatial and thermal) resolution. Thermal cameras using focal plane array sensors have higher resolutions but are expensive and are little used. The potentially large scale usage within the automotive industry may soon reduce their cost significantly, and adds impetus to research and usage in non-military applications.

Increased (thermal) resolution of thermal cameras is opening new applications such that the footprints of the would-be intruder may remain for a sufficient time after traversing a secure area to enable detection by a suitably programmed AI system. The use of this thermal data does not appear to

have been addressed in the literature, though footprints are a well known source of forensic evidence (de Chazal, 2005). The need then is for suitable methods to detect the thermal trail.

Image analysis using oriented filters to detect features at particular orientations is well established. Freeman used quadrature pairs to allow both phase and orientation to be adaptively controlled and thus detected features with those parameters (Freeman, 1991). The discretisation problem in orientation and scale of many of these types of filters was addressed by Perona who stored the response of families of linear filters on a continuum of orientations and scales (Perona, 1995).

Morphological image operators are useful in extracting image features such as shape, convex-hull and skeleton.

In this paper these principles are combined with feature orientation to produce a direction-dependent dilation function, which combines some of the disparate blobs in certain footprint images. Thermal images of footprints are generally transient and of low contrast as discussed in section 2. A model for such images is proposed in section 3. The development of the function is described in section 4, and its application to a low contrast footprint image is presented in section 5.

2. Human thermal footprint images

Typical thermal footprints are presented in Figure 1. A shoe both reduces and spreads the flow of thermal energy such that the shoe print rarely reveals the foot shape. The outsole of a shoe is sometimes made of different materials, such that one provides a source and the other a sink for thermal energy. Much information is contained in the rate of change of intensity rather than in the intensity itself. An example is presented in Figure 1(c), and it is this image which is of particular interest here, in which the outer part of the shoe (leather) is a sink for energy while the inner area (rubber) is a source.

3. Low contrast image model

The particular type of image under investigation is typically of low contrast, due mainly to the transient nature of the transfer of thermal energy from shoe to floor during normal human gait. It has been found that the energy transfer is bi-directional, depending on the number and type of outsole materials. For this reason the image model used contains an area both of higher temperature and lower temperature than the background. With the background modelled as mid-grey, and higher temperatures towards white, an image model is obtained as presented in Figure 2(a). Gaussian noise of zero mean and standard deviation 0.0005 (assuming full-scale is 1.0) has been added to give a similar image to that obtained by a thermal camera. The histogram of this image is presented in Figure 2(b), in which the extremes of the distribution tails represent the information in the image. A well known and straightforward method of increasing the contrast of such images is histogram equalisation. After application to the image in Figure 2(a), the resultant image is presented in Figure 2(c), together with its

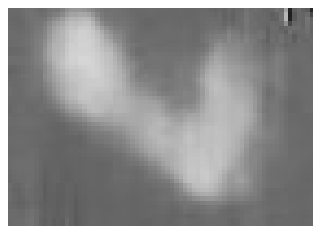


Figure 1(a) Footprint without shoe

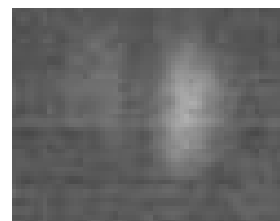


Figure 1(b) Footprint with single material outsole



Figure 1(c) Footprint with dual material outsole

histogram in Figure 2(d). It is apparent that the information in the image is now at the extremes of the greyscale and as such is more easily extracted from the image (by thresholding) than in the original image.

4. Steerable morphological operator

The morphological operation of dilation is defined in (1).

$$A \oplus B = \left\{ z \mid \left(\hat{B} \right)_z \cap A \neq \emptyset \right\} \quad (1)$$

Where: A is the image,
B is the structuring element, and
 \emptyset is the empty set

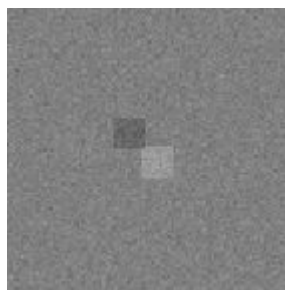


Figure 2(a) Low contrast image model

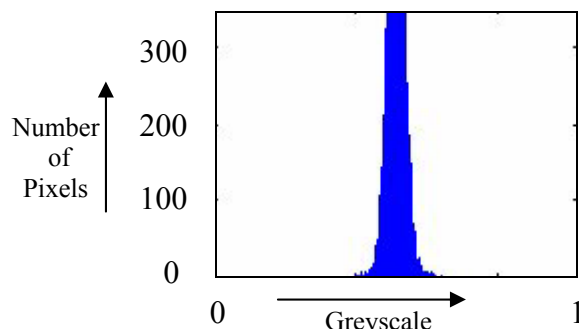


Figure 2(b) Histogram of low contrast image

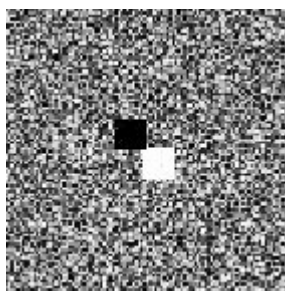


Figure 2(c) Histogram equalised image

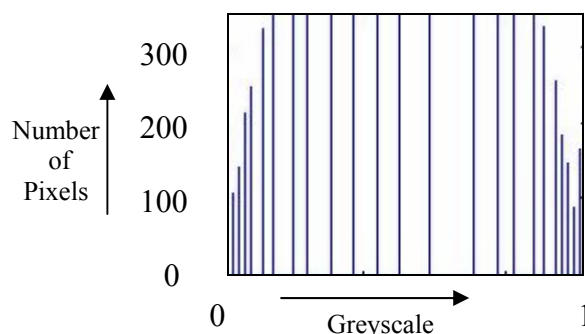


Figure 2(d) Histogram of equalised image

The technique is frequently used to bridge gaps in noisy images (Gonzalez, 2002). This is successful for omnidirectional operators, or using a unidirectional structuring element if the direction is known. When the direction is unknown, there is a risk of failing to bridge the gap or to add clutter to the image. In those situations it would be useful to be able to steer the direction of the dilation according to local image constraints.

For the class of image considered in section 2, the footprint intensity between areas of highest and lowest temperature is almost indistinguishable from the background. When the image is thresholded, the footprint therefore apparently contains large holes, as seen in Figure 3(e). This is due to averaging of hot and cold on the outsole and results in an apparent lack of thermal information. However, there is a large change of thermal intensity, and a measure of intensity slope thus contains some of the information not present in the intensity image.

It is seen that the edge direction contains information regarding the most probable direction of the nearest neighbouring portion of the footprint, indicated in Figure 3(c). The proposed method of dilation chooses a structuring element from the available unidirectional varieties dependent on the local edge direction, and thus bridges some of the gaps in the thresholded image.

5. Applying the operator

Starting with the image in Figure 1(c), the equalised image is presented in Figure 3(a). Edge information is detected using a Sobel operator, and its output presented in Figure 3(b). The direction of the edge at each edge pixel is presented diagrammatically in Figure 3(c) and encoded in Figure 3(d). The equalised image is thresholded in Figure 3(e), and the resultant image after dilation using the steerable structuring element is presented in Figure 3(f).

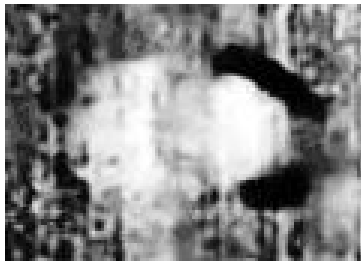


Figure 3(a) Histogram equalised image



Figure 3(b) Output of Sobel edge operator

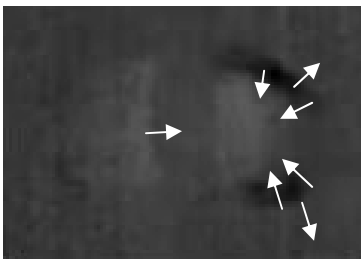


Figure 3(c) Indication of edge direction

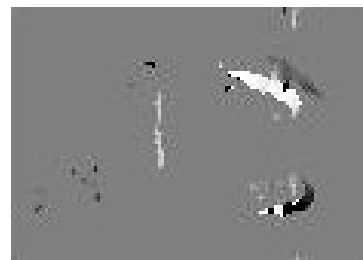


Figure 3(d) Edge direction encoded



Figure 3(e) Thresholded image

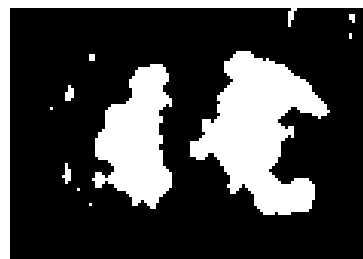


Figure 3(f) Blobs combined using steerable operator

6. Conclusions

A method of extracting footprints from low-contrast thermal images has been presented. A novel technique uses edge direction to steer a structuring element to enhance the image. This has been demonstrated by dilating a binary image, though the technique should be extendible to other morphological operations and to greyscale images.

7. References

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